

Assembly Manual

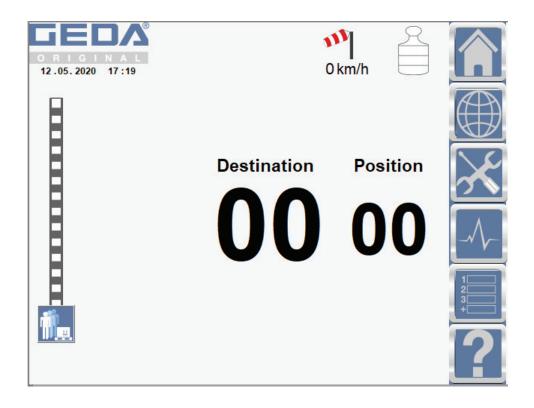




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1 General information

1.1 Information about the Assembly Manual

You will come across a series of illustrations and symbols while reading this manual. These are intended to help you navigate and understand this manual. The different meanings are explained below.

Text format	Meaning
Bold type	Emphasises particularly important words/sections
List	Identifies lists level 1
– List	Identifies lists level 2
(brackets)	Item numbers
Task instruction	Task instructions for personnel. Always given in chronological order

Images

The illustrations used refer to a specific machine type. They may only constitute a schematic representation of other machine types. The fundamental function and operation are not affected by this.

The structural elements in this operating manual appear as follows and have the following meaning:

1.2 Identification data

The touch display described in this manual is used in various different GEDA hoists.

Depending on the type of hoist or the design of the hoist, the display or the description of functions may vary.

Documentation version: 2021-07

1.3 Information about the author and industrial property rights

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1.4 Assembly, service/maintenance specialist

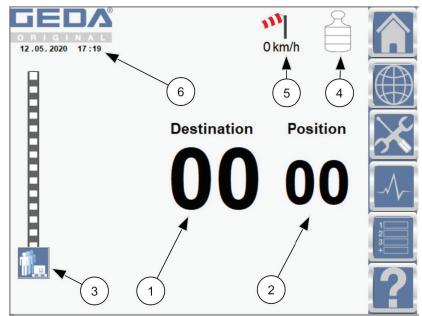
Persons authorised to carry out assembly tasks

A person who, due to qualified professional education, training and experience, is able to recognise risks and potential hazards during assembly/maintenance/repair work on the machine and subcomponents and can rectify these by introducing appropriate measures. 2

Description and operation

This manual describes the functions and control elements that require you to enter a password on the touch display. Restricted access group (assembly/maintenance).

The text elements in the figures is shown in English. All text elements are displayed on the touch panel in the selected language.



4

5

6

Load indicator

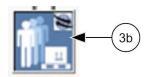
Wind force (optional)

Date/time display

Fig. 1: Touch display (HMI) car 1

- 1 Destination
- 2 Current car position
- 3 Current position of car on mast
- **1**-3a

3a Symbol: Hoist without remote service



3b Symbol: Hoist with remote service



Fig. 2: Touch display (HMI) car 2

AHOMEDCurrent code listBLanguage selectionELanding level detailsCOperating dataFHelp

Touch display at the ground station (option)



Fig. 3: Touch display (HMI) ground station

1 Destination	

- 2 Current car position
- 3 Load indicator
- 4 Wind force (option)
- A HOME
- C Current code list
- D Maintenance

2.1 Current code list

Display of the current code list

> Tap the symbol (D).



Fig. 4: Code list symbol "D"

✓ Only the currently pending codes are displayed.



Fig. 5: Current CODE list

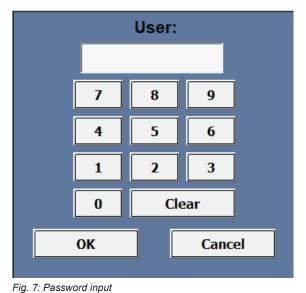
Display of the code history

➤ Tap the symbol (11).



Fig. 6: Code list

- ➢ Enter login.
- Password (name): 86663
- ➢ Confirm with "OK".



 ✓ The codes for at least the last 180 days are displayed.

13	R I G I N A L .05.2020 10:32		0 km/h	1.
Eve	ent Time	Descriptio	Event Text	\mathbb{A}
+	5/13/2020 10:30:	Code 23 ·	Blindstecker Montage- oder Fangprobensteuerung (a	\bigoplus
٠	5/13/2020 10:30:	Code 23 ·	Blindstecker Montage- oder Fangprobensteuerung (a	
٠	5/13/2020 10:30::	Code 15 ·	Dachluke ist geöffnet	
•	5/13/2020 10:23::	Code 15 ·	Dachluke ist geöffnet	
٠	5/13/2020 10:12:0	Code 37 ·	Frequenzumrichter Fehler	2
ŧ	5/13/2020 10:12:0	Code 46 ·	Überwachung Mastverbindung	
ŧ	5/13/2020 10:12:0	Code 27 ·	NOT-HALT Blindstecker Dach	$\neg \Lambda$
Ŧ	5/13/2020 10:12:0	Code 16 ·	Montagesteg Seite 2 (ausgefahren)	Y
٠	5/13/2020 10:12:0	Code 15 ·	Dachluke ist geöffnet	1
ŧ	5/13/2020 10:12:0	Code 14 ·	Fangvorrichtung hat ausgelöst	2
ŧ	5/13/2020 10:08:	Code 03 ·	Tür «A» geöffnet	÷
₽	Out of interval	Code 15 -	Dachluke ist geöffnet	6

Fig. 8: Code history

2.2 Programming help section

> Tap the help symbol (F).



Fig. 9: Help symbol "F"

- → A menu overview for which "Help" is available is displayed.
- > Tap the field for which you need help.

O R I G I N A L 04.05.2020 11:50	Help Teaching	
	Legende	
	Teaching	\times
	Teach basic	
	Teach landing level doors	
	Delete landing levels	2
	Teach expert	≥?

Fig. 10: Help topics

- \rightarrow The work steps are shown in sequence.
- ✓ When a step has been completed successfully, it is shown with a green background.

Legend



Fig. 11: Legend

Programming stop positions

D R	G I N A L 15. 2020 11 : 51	Help Teaching	1
1	Assembly control	Position 0 mm	
2	Key switch Teaching set to position «On»	٢	
			10 20 30 +0
	<		

Fig. 12: Programming stop positions 1

Help Teaching	Â
۲	\times
۲	
Position -2 mm	
	≥?
	Teaching



Fig. 13: Programming stop positions 2

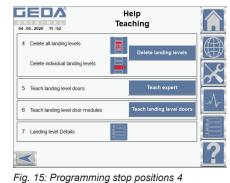


Fig. 14: Programming stop positions 3

Programming stop positions (Basic)

R I G I N A L 0.00.0000 00:00	Teach basic Position 0 mm	
1 Actuate button (Operating panel)	(1) 0,5 sec	¢
2 Open the released doo	or 👘 👬 max. 10cm	$\left \right\rangle$
3 Landing level input (HMI)	Landing Iteret XX	
4 Actuate button (Operating panel)	(+) Sec => Successful (HMI)	
5 Close the released doo		

Fig. 16: Programming stop positions (Basic) 1

) R	EDA 15. 2020 13 : 33	Teach basic Position -2 mm	Â
1	Actuate button (Operating panel)	() 0,5 sec	Œ
2	Open the released door	10cm	\mathbf{x}
3	Landing level input (HMI)	XX IIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIIII	
4	Actuate button (Operating panel)	€ Successful (HMI)	
5	Close the released door		?

Fig. 17: Programming stop positions (Basic) 2

Teaching the electric module at the stop positions

1	Car standing at taught landing level Open the released door	1	
2	Actuate button (HMI)	┦ ⇒ ┦	Ì
3	Actuate button (Etage)	S sec	
4	(HMI)	10 sec	Ì
5	Close the released door	÷	ł

Fig. 18: Teaching the electric module for stop at landing level

Deleting stop positions

	Delete all landing levels (HMI)	Delete ind	lividual landing levels (HMI)
		Actuate button	
2			evel Landing Input K K
	Actuate button (Operating panel)		Successful (HMI)

Fig. 19: Deleting stop positions

Programming stop positions (Expert)

Shown for hoists with the "Premium package" option.

	GINAL 05.2020 13:46	Teach expert Position 0 mm	L
1	Door selection (HMI)	Door release B A	
2	Actuate button (Operating panel)	4 0,5 sec	\langle
3	Open the released door	10cm	
4	Landing level input (HMI)	Landing level XX	
		0	_ 2



Fig. 20: Programming stop positions (Expert) 1

Fig. 21: Programming stop positions (Expert) 2

2.3 Programming modes

2.3.1 **Programming stop positions**

The assembly control remains connected.

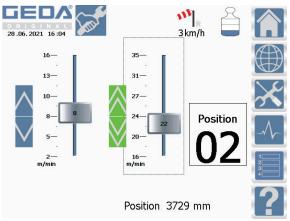


Fig. 22: Display for assembly mode

- > Open the roof switch box.
- Turn the "Teach" key switch to the "On" position.



Fig. 23: Key switch in programming mode

→ The STOP AT LANDING LEVEL button (50) flashes slowly.



 ✓ The touch display automatically switches to "Basic" programming mode.

09.03.2020 15:46	₩ 0 km/h 🗍 🚺
Landing level	Position 0
Position	0 mm

Fig. 24: "Basic" programming mode



With the Premium package, the touch display switches to "Expert" programming mode.

2.3.2

1

To prevent incorrectly programmed landing level positions (stop positions) when using the hoist at different locations, the landing positions must be deleted before every new installation!

- ➤ Tap the symbol (41).
 - ✓ The symbol lights up green as confirmation.

Deleting stop positions

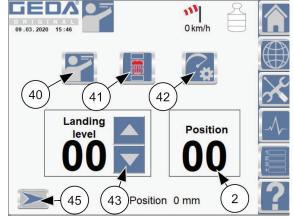


Fig. 25: Deleting stop positions

- Press the STOP AT LANDING LEVEL button (50) for 5 seconds.
 - → As confirmation, the STOP AT LANDING LEVEL button flashes faster.



✓ All programmed stop positions have now been deleted!

A \checkmark is shown on the touch display.

2.3.3 Setting the lifting speed

The lifting speed can be adjusted for precise positioning of the car at the stop position.

> Tap the symbol (42).

- The lifting speed for the slow level can be adjusted with the slider (31).
- The lifting speed for the fast level can be adjusted with the slider (32).

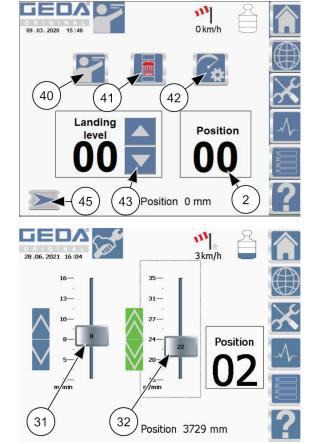


Fig. 26: Setting the lifting speed

- 2.3.4 **Programming stop positions (Basic)**
- 2.3.4.1 Programming stop positions with the G-SAC control [single automatic control]



A landing level safety gate first has to be installed at the stop position!

Travel to the first landing level (stop position) using the assembly control and position it there precisely aligned with the landing level safety gate.



The car floor and the sill of the landing level safety gate must be at exactly the same level! (Tolerance ±1 cm)

Briefly press the STOP AT LANDING LEVEL button (50).





The car door on the "B side" of the car is programmed by default as "Access to building" on this control unit.

Open the car door at the landing level safety gate approx. 10 - 20 cm within the next 5 seconds.

Check whether the landing level safety gate is in front of the slightly open car door.

A DANGER



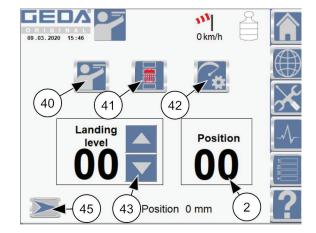
- Lethal hazard fall from the car
- Never open the car door by more than approx. 20 cm during programming.



The STOP AT LANDING LEVEL button (50) has to be pressed again if the car door is not opened within 5 seconds.

2

Car position



- 43 Setting landing levels: UP button: Preselect landing levels 1 to 9 (11 – 19, 21 – 29, ...) DOWN button: back from landing levels 9 to 0 (19 – 10, 29 – 20, ...) Max. 99 landing levels
- Press the STOP AT LANDING LEVEL button (50) for approx. 5 seconds until a @ appears on the touch display.
- Release the button again.
 - → As confirmation, the STOP AT LANDING LEVEL button flashes faster.



A 🔨 is shown on the touch display.

- Close the open car door again.
 - ✓ This completes programming of this stop position.



Program the other landing levels as described.

Checks after programming

- Did the car stop at the selected stop position?
- Is the floor of the car at the same level as the landing level (sill of the landing level safety gate)?



Carry out a function test at each stop position. The landing level position can also be programmed to correct individual stop positions.

2.3.4.2 Additional programming for the "G-ICSB" control unit

[intelligent call system]

The stop positions are programmed on this control unit as described in chapter 2.3.4.1 Programming stop positions with the G-SAC control. The "G-ICSB" control unit has electric modules with call control at the landing level safety gates. These electric modules have to be assigned to the programmed stop positions.

"Basic" programming mode

- > Tap the symbol (40).
 - ✓ The symbol lights up green as confirmation.

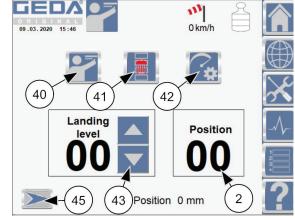


Fig. 27: Assigning electric modules

Electric module with call control

The call control button (60) flashes on all installed electric modules.

Start ID search

- > Press the CALL button for 5 seconds.
- Release the button as soon as the flashing sequence of the CALL button changes.



Fig. 28: Assigning electric modules

The button flashes for 6 seconds during the ID search.

After a two second pause, the button flashes the new electric module ID.

After teaching the electric module, the buttons at the stop positions stop flashing and the button (40) on the touch display starts flashing green.

A \checkmark is shown on the touch display.

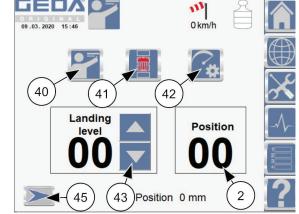
Programming has been successfully completed and the button on the touch display turns blue.

2.3.5 "Expert" programming mode – additional functions

2.3.5.1 Programming stop positions (Expert)

This chapter only applies to hoists with the "Premium package" option.

- Tap the arrow symbol (45).
 - ✓ The display changes to "Expert" programming mode.





The arrow symbol is shown only for hoists with "Expert" programming mode.

This offers the option of changing between the "Basic" and "Expert" programming modes.

Tap "A" and/or "B" (49) to select the desired car door.

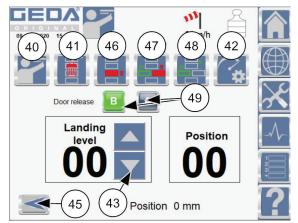


Fig. 29: "Expert" programming mode

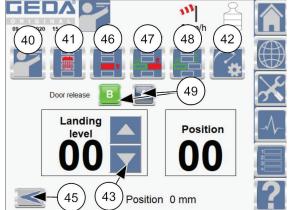
- 40 Assign button for electric modules. Refer to chapter 2.3.4.2 Additional programming for the "G-ICSB" control unit
- 41 Delete button for stop positions. Refer to chapter 2.3.2 Deleting stop positions
- 43 Buttons for entering the landing level number. Refer to chapter 2.3.4.1 Programming stop positions with the G-SAC control



Programming of the stop positions can be continued after selecting the car door. The car door can be selected for every stop position and "Expert" programming mode therefore remains active until programming of the stop positions has been completed.

2.3.5.2 Deleting individual stop positions

- Use the arrow symbols (43) to select the stop position to be deleted.
- ➤ Tap the symbol (46).
 - ✓ The button lights up green to confirm the selection.



- Press the STOP AT LANDING LEVEL button (50) for 5 seconds.
 - → As confirmation, the STOP AT LANDING LEVEL button flashes faster.



A \checkmark is shown on the touch display.

2.3.5.3 Changing the stop position



A landing level safety gate first has to be installed at the stop position!

- Travel to the new stop position using the assembly control and position it there precisely aligned with the landing level safety gate.
- ➤ Tap the symbol (47).
 - $\rightarrow\,$ The button lights up green to confirm the selection.
- > Briefly press the STOP AT LANDING LEVEL button (50).

Open the car door at the landing level safety gate approx. 10 - 20 cm within the next 5 seconds.

Check whether the landing level safety gate is in front of the slightly open car door.

A DANGER



Lethal hazard – fall from the car

Never open the car door by more than approx. 20 cm during programming.



The STOP AT LANDING LEVEL button (50) has to be pressed again if the car door is not opened within 5 seconds.

- Press the STOP AT LANDING LEVEL button (50) for approx. 5 seconds until a @ appears on the touch display.
- Release the button again.
 - → As confirmation, the STOP AT LANDING LEVEL button flashes faster.



A \checkmark is shown on the touch display.

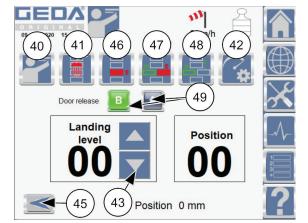
- Close the open car door again.
 - $\checkmark~$ This completes programming of this stop position.



Program the other landing levels as described.

2.3.5.4 Adding stop positions

- Use the arrow symbols (43) to select the new stop position.
- ➤ Tap the symbol (48).
 - ✓ The button lights up green to confirm the selection.



- Press the STOP AT LANDING LEVEL button (50) for approx. 5 seconds until a @ appears on the touch display.
- Release the button again.
 - → As confirmation, the STOP AT LANDING LEVEL button flashes faster.



A \checkmark is shown on the touch display.



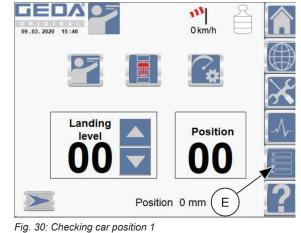
A landing level safety gate also had to be installed for the new stop position. The electric module on the landing level safety gate (call control) has to be assigned to the new stop position. Refer to chapter 2.3.4.2 Additional programming for the "G-ICSB" control unit

The stop positions above will automatically be increased by one landing level number.

2.3.6 Checking the car position

The parameters of the programming can be checked after programming the stop positions.

Tap the "Landing level details" symbol (E).



 The information for the first 9 landing levels (if available) is displayed.

GE			D	oor open				
O R I G I N A L 29.04.2021 15:44			Landing level call button					
Landing I	evel Position	Offset	Door release	Landi	ng lev	el ID		
0	-50 mm	0 mm	AB	101	0	0		
1	934 mm	0 mm	AB	0	0	0		
2	1948 mm	0 mm	A B	0	0	0		
3	2990 mm	0 mm	AB	0	0	0	\sim	
4	4022 mm	0 mm	AB	0	0	0		
5	4999 mm	0 mm	AB	0	0	0		
6	6098 mm	0 mm	AB	0	0	0		
7	7199 mm	0 mm	AB	0	0	0		
8	8112 mm	0 mm	AB	0	0	0		
9	9017 mm	0 mm	AB	0	0	0		
	Position -10 mm							

Fig. 31: Checking car position 2

Display:

Landing	Position in	Offset (fine	Released car door
level no.	mm	adjustment) in	(for the landing
0, 1, 2,		mm	level)

Landing level ID (only for call control) Assigning the electric module



The fine adjustment can only be made in the password-protected area.

2.3.7 Fine adjustment of the car position

Tap directly on the "Offset" value, e.g. for landing level 1 (1).

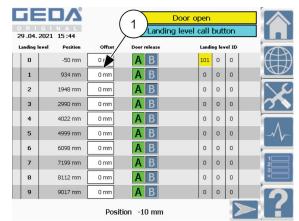


Fig. 32: Fine adjustment of car position 1

- ➢ Enter login.
- Password (name): 86663
- Confirm with "OK".

	User:			
7	8	9]	
4	5	6]	
1	2	3]	
0	Cle	ear		
ОК		Canc	el	

Fine adjustment of car position 1



After one minute without any input in the menu selection, the touch display automatically returns to the operating display.

Measure the height difference between the floor of the car and the sill of the landing level safety gate and correct this value in the input field if required.

Correction value = $\pm 50 \text{ mm}$

Low Limit: 0						
High Limit: 0						
Current Val: 000						
Value: 000						
7	8	9				
4	5	6				
1	2	3				
+/-	0	•				
Cle	ear					
0	к	Cancel				
Eig. 22: Eine adjustment of ear position 2						

Fig. 33: Fine adjustment of car position 2

2.4 **Protected section** \geq Tap the GEDA GEDA M 0 km/h logo (G). G 12.05.2020 17:16 Destination Position 02 \succ Tap the symbol (20). GEDA M 0 km/h 09.03.2020 13:56 20 ➢ Enter login. User: > Password (name): 86663 Confirm with "OK". \geq 7 8 9 4 5 6 1 2 3



After one minute without any input in the menu selection, the touch display automatically returns to the operating display.

0

OK

Clear

Cancel

✓ The menu overview is displayed.



Fig. 34: Overview – protected area

27 Only displayed if the "Premium package" has been selected as an option

2.4.1 Load display

After installation of the hoist and accessories (assembly crane, etc), the tare weight of the car can be set to "0".

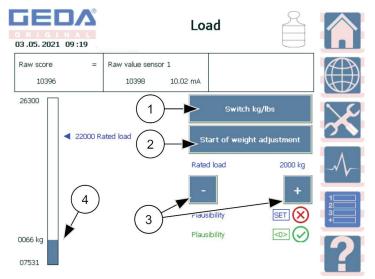


Fig. 35: Overview of load display

- 1 Switch weight units (kg/lbs)
- 2 Start load adjustment
- 3 Set nominal load
- 4 Load display

The bar shows the current weight. The bar colour is dynamic. The current weight is shown in kg or lbs to the left of this.



Installing additional equipment (e.g. additional floor covering made of steel/aluminium) increases the tare weight. This reduces the load capacity of the car accordingly.

Prerequisite:

Only the operator is in the car!

Starting the load adjustment

- > Tap the field (2).
 - \rightarrow "Start load adjustment" is active and the field turns green.



This display appears.

The setting process has to be continued on the touch display at the ground station!

For settings, please refer to chapter 2.4.1.1 Settings at the ground station

 \rightarrow For hoists that do not have a touch display at the ground station, a pop-up window is displayed for the adjustment.

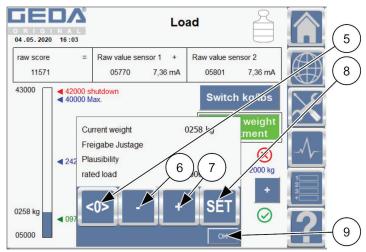


Fig. 36: Pop-up window for setting the load in the car

Prerequisite:

Only the operator is in the car!

Setting the tare weight of the car to "0"

> Tap the field (5).

Setting the nominal load

- Load the car to the nominal load.
 - $\rightarrow\,$ The operator is in the car with the nominal load.
- ➤ Use "-" and "+" (6, 7) to set the weight limit.
- Confirm the input by tapping the field (8).
- > Press "OK" (9) to exit the input window.

2.4.1.1 Settings at the ground station

Go to the ground station and make the other settings on the control unit there.



Fig. 37: Setting the load at the ground station

Prerequisite:

The car is empty!

Setting the tare weight of the car to "0"

After installation of the hoist and the accessories (e.g. assembly crane, etc), the tare weight of the car can be set to "0".

- > Press the button (5).
 - → The button lights up if the conditions "Enable", "Adjustment" and "Plausibility" are in place.

Setting the nominal load

- > Load the car to the nominal load.
- ➤ Use "-" and "+" (6, 7) to set the weight limit.
 - $\rightarrow\,$ If an input limit is reached, the LED for the respective button goes out. It is shown accordingly with max. or min.
- > Confirm the input by tapping the field (8).

2.4.2 Setting date/time

The display of the date and time underneath the GEDA logo can be changed to the local time. Date and time are changed in the PLC, on the touch display and on the frequency converter (FC).

➤ Tap the field (22).

Entering/changing time

corresponding input

and date

 \succ Tap on the

field.

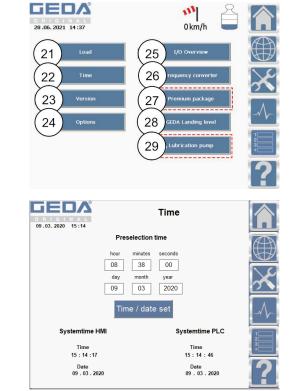
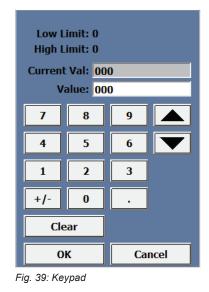


Fig. 38: Changing date/time

- Enter the value on the keypad that is displayed and confirm with "OK".
 - \rightarrow Repeat for all input fields.



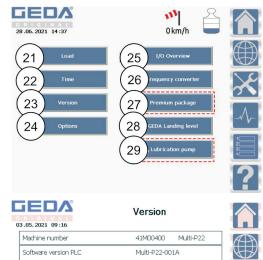


The time is controlled by the PLC. This means the PLC synchronizes the time on the touch display and on the frequency converter.

2.4.3 Softwareupdate and Version

Viewing the software version

 \succ Tap the field (23).



- → The software version for the current hardware is displayed.
- \succ Tap the field (a).

Machine number	41M00400 Multi-P22	Æ
Software version PLC	Multi-P22-001A	\mathbb{A}
Serial number PLC	S C-M8B950222020	
Safety CRC PLC	94F738A4	\sim
Software version VFD	Multi-P22-001A	É
Serial number VFD	02.05.00.17	$ \neg \wedge $
Software version HMI	Multi-P22-001A	
Software version HMI ground station	Multi-P22-001A	1
Software version GEDA-BUS	V1.82	,÷

Fig. 40: Viewing the version

- PLC Programmable logic control
- HMI Human machine interface (touch display)
- VFD Variable frequency drive (frequency converter)

2.4.3.1 Updating the software

Saving the settings

Tap the corresponding field to transfer the settings on the PLC to the touch display (HMI) (a) and from the HMI to the PLC (b).

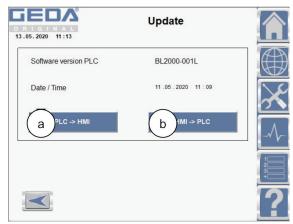


Fig. 41: Update

If the PLC has been replaced or updated, the settings (e.g. for the Premium package or the load) no longer have to be carried out.

Downloading log files

The log files are stored in the directory MMCMemory\GEDA on the touch display.

- Codes Alarm history CSV file
- Logger data logger CSV file
- Parameter set values CSV file
 - Premium package number ...
 - Load settings
- Tap the field (c) to save the log files to a USB storage medium.

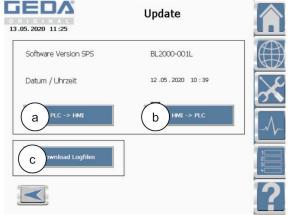
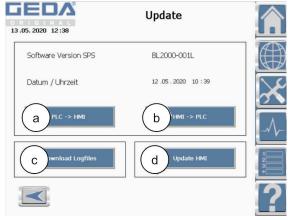


Fig. 42: Downloading log files 1

Software update for touch display (HMI)

The software for the touch display can be updated with a USB storage medium.

- Connect the storage medium to the touch display.
 - \rightarrow The field (d) is shown.





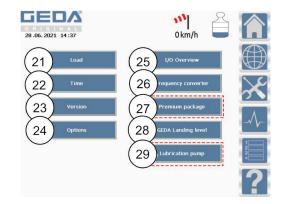


An update is carried out only if a directory "\AutoUpdate" with the data is available on the storage medium.

2.4.4 Options

Viewing/changing options

➤ Tap the field (24).





Subsequently configured options can be selected here.

Add on Premium package

- Enter the package number in the field (a).
 - ✓ This enables the settings for the Premium package.

28.06.2021 14:05 a Options		
Premium packare		
Entrance system Landing level		\geq
Car heating		
Interlock cam in enclosure barrier, release		
Wait time driving commands	11 sec	
Offset	00	
Ground Station HMI		*)?

Fig. 44: Options

The Premium package can contain the following, for example:

- Homing wind speed
- Homing time setting
- Material transport between two defined stop positions (landing levels)
- "Expert" programming mode
- Remote service

2.4.5 Displaying current inputs/outputs

> Tap the field (25).



✓ The current inputs and outputs for the control in the switch box for the car control are displayed.



Fig. 45: Example for display of car inputs/outputs

- 55 Display of HMI system variables
- 56 Display of the signals (technological)
- 57 Display of the individual assemblies with description of the signals
- 58 Display of the EMERGENCY STOP line



For some machine types, this information can also be displayed for the switch box on the car roof.

- > Tap the symbol (59).
 - ✓ The display changes between the car and car roof switch box.

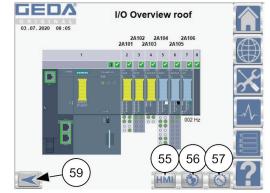
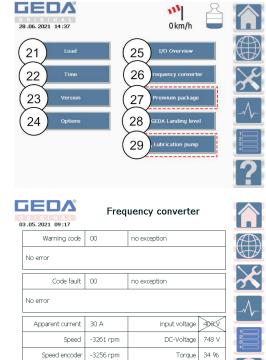


Fig. 46: Example for display of car roof inputs/outputs

Display of the parameters of the frequency converter 2.4.6

➤ Tap the field (26).



The parameters for \checkmark the frequency converter are displayed.

Warning code	00	no exception	(4
No error				Ł
Code fault	00	no exception		}
No error				\mathcal{A}
Apparent current	30 A	input voltage	Jac	
Speed	-3261 rpm	DC-Voltage	748 V	
Speed encoder	-3256 rpm	Torque	34 %	·

Fig. 47: Display of frequency converter parameters



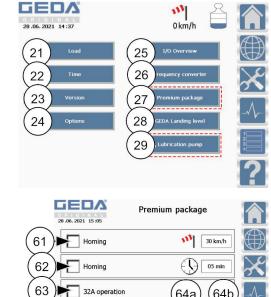
The input voltage is shown only when the hoist is not moving.

✓ Other parameters for the frequency converter are displayed.

Software version VFD			Multi-P22-	-001A	A
Serial number VFD		02.05.00.17		\overline{A}	
2.3.x.x			2.5	.х.х	
Read	Index 0x2b6d	Subindex	Value IP 000 000 00	0 000 Write	
STO	PLC	FC FC	status	release	
channel A	1	1	OK		10
channel B	1	1	OK		30

Fig. 48: Display of frequency converter parameters 2

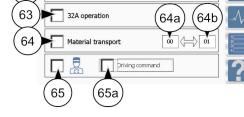
2.4.7 Settings for the "Premium package option"



 ✓ The options in the "Premium package" are shown.

Activating an option

- Tap the desired option.
 - ✓ This activates the option and displays a ♥.



```
Fig. 49: Premium package 1
```

65 Operating options for "Liftboy" mode a

- ⁶¹ Wind speed setting at which the hoist has to move to the ground station. A shown next to the windsock in the operating display.
- 62 If the hoist is not used for the number of minutes entered here, it moves to the ground station. A sis shown next to the time in the operating display.
- 63 he hoist is operated in 32 A mode. The travelling speed is reduced, and the load capacity may be reduced.
- 64 Material transport between two defined stop positions.
- 65 Activate "Liftboy" mode.

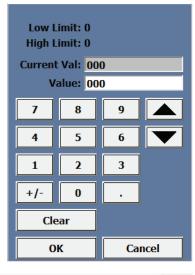
Operating options

65a Driving command Driving command

When the button is deactivated, driving commands can only be processed via the keypad or rotary/push button. Operation by tapping on the touch display is not possible.

Setting options

Enter the desired value on the keypad that is displayed and confirm with "OK".



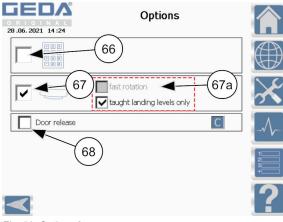


Fig. 50: Options 2

67 Operating options with rotary/push button a

- 66 The car control is a keypad
- 67 The car control is a rotary/push button
- 68 Door release for a door on the C-side of the car. (Not possible for every type of hoist!)

Operating options

67a	Fast rotation Fast rotation	The landing level numbers are increased and decreased faster on the display.
	Taught landing levels only Taught landing levels only	Only the programmed landing levels are displayed.

2.4.7.1 Material transport

Activate material transport (1) and enter the landing level numbers (2).

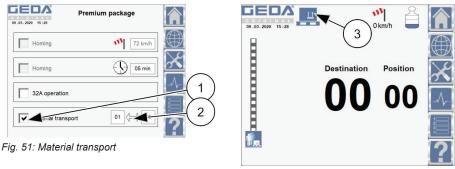


Fig. 52: Operating display for material transport



Only landing level modules 1 and 3 are activated. All others are flashing and deactivated.

Example for material transport between landing levels 1 and 3

- Load the hoist at landing level 1, close the door and press the button on the landing level module.
 - \rightarrow The button lights up and the hoist moves to landing level 3.
- Unload the hoist at landing level 3, close the door and press the button on the landing level module.
 - \checkmark The button lights up and the hoist moves to landing level 1.

If a touch display is installed at the ground station, the material transport (1) will displayed.



Fig. 53: Display of material transport at ground station

2.4.8 Landing level diagnostics

> Tap the field (28).



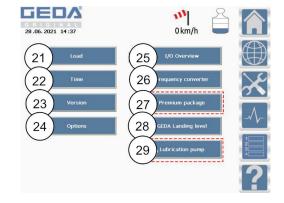
- An overview of the stop positions (ground station and landing levels) with their function statuses is shown.
- Door open
- Door closed
- Hoist called (button on landing level module pressed)

O RIGINAL 03.05.2021 09:21 Ground Station	Door open	
	Landing level call button	
Floor diagnosis		\mathbf{N}
1 2 3 4 5	6 7 8 9 10	
11 12 13 14 15	16 17 18 19 20	
21 22 23 24 25	26 27 28 29 30	
31 32 33 34 35	36 37 38 39 40	//
41 42 43 44 45	46 47 48 49 50	
51 52 53 54 55	56 57 58 59 60	
61 62 63 64 65	66 67 68 69 70	3
71 72 73 74 75	76 77 78 79 80	
81 82 83 84 85	86 87 88 89 90	17
91 92 93 94 95	96 97 98 99 RUN	

Fig. 54: Overview of landing level function statuses

2.4.9 Lubrication device

> Tap the field (29).



✓ The lubrication device variant is displayed with the possible functions/settings in each case.

2.4.9.1 Lubrication device variant 1

 ✓ Information on the lubrication device is displayed.

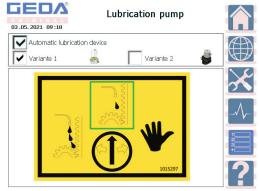


Fig. 55: Lubrication device variant 1 (automatic mode)

2.4.9.2 Lubrication device variant 2

Adjusting the lubrication quantity

The lubrication quantity can be adjusted with the slider (a).

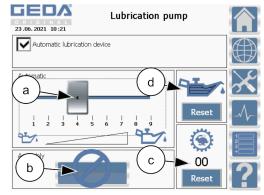


Fig. 56: Lubrication device (automatic mode)

- b Lubrication during assembly mode is not possible in automatic mode
- c Number of "Travel slowly" messages
- d Fill level of the lubrication device

Adjusting lubrication during assembly mode

- > Tap the field (f).
 - Lubrication for the gear racks is not switched on for 20 minutes.

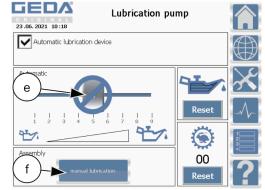


Fig. 57: Lubrication device (assembly mode)



е

The lubrication device is only active during upward travel. If the message "Lubrication device empty" (fill level orange)

Adjustment of lubrication quantity not possible in assembly mode

appears, the hoist will slow down after a certain time. The counter (c) is increased by 1. The message can be acknowledged by tapping Reset. The hoist then moves faster again for a limited period.



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